

Mathematical graphics with MuPAD

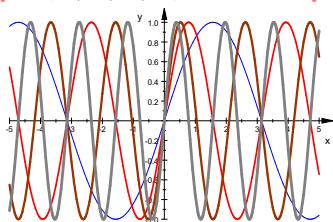
The structure of MuPAD graphs

```
[info(plot)
Library 'plot': graphical primitives and functions for two- and three-dimension\
al plots

-- Interface:
plot::AmbientLight,    plot::Arc2d,                  plot::Arc3d,
plot::Arrow2d,          plot::Arrow3d,                plot::Bars2d,
plot::Bars3d,           plot::Box,                   plot::Boxplot,
plot::Camera,           plot::Canvas,                plot::Circle2d,
plot::Circle3d,         plot::ClippingBox,             plot::Cone,
plot::Conformal,        plot::CoordinateSystem2d,   plot::CoordinateSystem3d,
plot::Curve2d,          plot::Curve3d,                plot::Cylinder,
plot::Cylindrical,      plot::Density,               plot::DistantLight,
plot::Dodecahedron,     plot::Ellipse2d,              plot::Ellipse3d,
plot::Ellipsoid,        plot::Function2d,             plot::Function3d,
plot::Group2d,          plot::Group3d,                plot::Hatch,
plot::Hexahedron,       plot::Histogram2d,            plot::Icosahedron,
plot::Implicit2d,       plot::Implicit3d,              plot::Inequality,
plot::Integral,         plot::Iteration,              plot::Line2d,
plot::Line3d,           plot::Listplot,               plot::Lsys,
plot::Matrixplot,        plot::MuPADCube,              plot::Octahedron,
plot::ODE2d,            plot::ODE3d,                 plot::Parallelogram2d,
plot::Parallelogram3d,   plot::Piechart2d,              plot::Piechart3d,
plot::Plane,             plot::Point2d,                plot::Point3d,
plot::PointLight,        plot::PointList2d,             plot::PointList3d,
plot::Polar,             plot::Polygon2d,              plot::Polygon3d,
plot::Prism,             plot::Pyramid,                plot::QQplot,
plot::Raster,            plot::Rectangle,              plot::Reflect2d,
plot::Reflect3d,         plot::Rootlocus,              plot::Rotate2d,
plot::Rotate3d,          plot::Scale2d,                plot::Scale3d,
plot::Scatterplot,       plot::Scene2d,                plot::Scene3d,
plot::Sequence,          plot::SparseMatrixplot,       plot::Sphere,
plot::Spherical,         plot::SpotLight,              plot::Streamlines2d,
plot::Sum,               plot::Sweep,                  plot::SurfaceSTL,
plot::SurfaceSet,        plot::Text2d,                 plot::Tetrahedron,
plot::Text3d,            plot::Transform2d,             plot::Transform3d,
plot::Transform3d,        plot::Translate2d,             plot::Translate3d,
plot::Tube,              plot::Turtle,                  plot::VectorField2d,
plot::VectorField3d,      plot::Waterman,              plot::XRotate,
plot::ZRotate,           plot::copy,                  plot::delaunay,
plot::easy,              plot::getDefault,            plot::hull,
plot::modify,
```

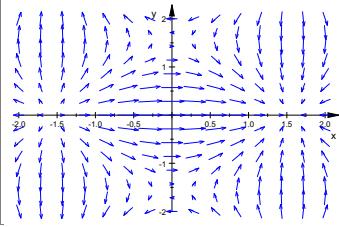
1 Function2d

```
G1 := plot::Function2d(sin(x), x=-5..5,
  LineColor=RGB::Blue,
  LineWidth=0.3*unit::mm
):
G2 := plot::Function2d(sin(2*x), x=-5..5,
  LineColor=RGB::Red,
  LineWidth=0.6*unit::mm
):
G3 := plot::Function2d(sin(3*x), x=-5..5,
  LineColor=RGB::Brown,
  LineWidth=0.8*unit::mm
):
G4 := plot::Function2d(sin(4*x), x=-5..5,
  LineColor=[0.5, 0.5, 0.5],
  LineWidth=1*unit::mm
):
plot(G1,G2,G3,G4) // here we plot objects G1,..,G4
```



2 Vector field

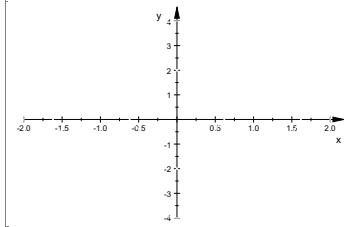
```
z := (x,y)->sin(x)*cos(y)
(x, y) → sin(x) cos(y)
F := diff(z(x,y),x):
G := diff(z(x,y),y):
V := plot::VectorField2d([F,G], x=-2..2, y=-2..2,
  Mesh=[15,15]
):
plot(V)
```



3 Curve2d

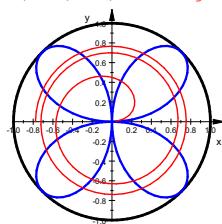
```
C1 := plot::Curve2d(
  [2*sin(3*t), 4*cos(5*t)], t=0..2*PI
):
plot(C1)

plot(plot::Curve2d([2*sin(3*x), 4*cos(5*x)],
  LineColorFunction = ((u, x, y, a) -> [(u-a)/5, (u-a)/5, 1]),
  a = -5..5))
```



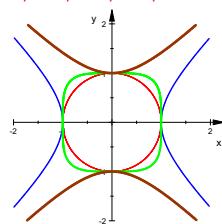
4 Polar coordinates

```
P1 := plot::Polar([1, alpha], alpha=0..2*PI,
  LineWidth=1, LineColor=RGB::Black
):
P2 := plot::Polar(
  [sin(2*alpha), alpha], alpha=0..2*PI,
  LineWidth=0.8, LineColor=RGB::Blue
):
P3 := plot::Polar([exp(-1/u^0.5), u], u=0.1..5*PI,
  LineWidth=0.5, LineColor=RGB::Red
):
plot(P1, P2, P3, Scaling=Constrained)
```



5 Implicit2d

```
I1 := plot::Implicit2d(x^2+y^2=1, x=-2..2, y=-2..2,
  LineColor=RGB::Red
):
I2 := plot::Implicit2d(x^2-y^2=1, x=-2..2, y=-2..2,
  LineColor=RGB::Blue,
  LineWidth=0.5
):
I3 := plot::Implicit2d(x^4+y^4=1, x=-1..1, y=-1..1,
  LineColor=RGB::Green,
  LineWidth=0.7
):
I4 := plot::Implicit2d(-x^2+y^2=1, x=-2..2, y=-2..2,
  LineColor=RGB::Brown,
  LineWidth=0.9
):
plot(I1, I2, I3, I4, Scaling=Constrained)
```



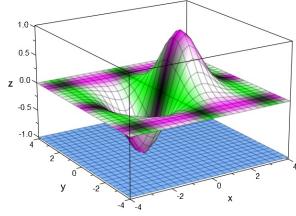
6 Function3d

```
K := (x,y,z)->[abs(sin(x)), abs(sin(y)), abs(sin(z))]:
```

```

F1 := plot::Function3d(
  1.7*x*exp(-1/2*(x^2+y^2)),
  x=-4..4, y=-4..4,
  FillColorFunction=K
):
F2 := plot::Function3d(-1, x=-4..4, y=-4..4):
plot(F1, F2)

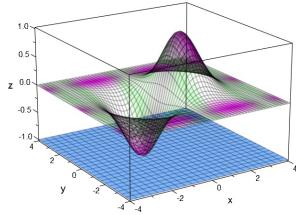
```



```

K := (x,y,z)→ [abs(sin(x)),abs(sin(y)),abs(sin(z)),abs(sin(z))]:
F1 := plot::Function3d(
  1.7*x*exp(-1/2*(x^2+y^2)),
  x=-4..4, y=-4..4,
  XMesh=50,
  YMesh=50,
  FillColorFunction=K
):
F2 := plot::Function3d(-1, x=-4..4, y=-4..4):
plot(F1, F2)

```

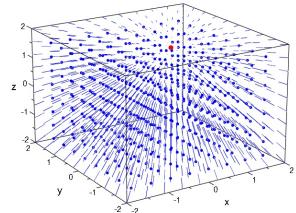


7 Vector field 3D

```

reset():
u := (x,y,z)→((x-1)^2+(y-1)^2+(z-1)^2):
F := diff(u(x,y,z),x):
G := diff(u(x,y,z),y):
H := diff(u(x,y,z),z):
V := plot::VectorField3d([F,G,H],
  x=-2..2, y=-2..2, z=-2..2,
  Mesh=[10,10,10],
  PointSize=1
):
P := plot::Point3d([1,1,1],
  PointColor=RGB::Red,
  PointSize=3,
  PointStyle=FilledCircles
):
plot(V,P)

```



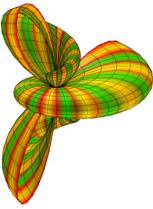
8 Surfaces

```

Cl := (u,v)→[u-trunc(u), v-trunc(v), 0]:
S1 := plot::Surface(
  [sin(u)*sin(v),
   sin(u)*cos(v),
   cos(u)*sin(v)],
  u=0..PI, v=0..PI,
  FillColorFunction=Cl
):
plot(S1)
Error: An arithmetical expression is expected. [sin]

A threefold shell
h := (x,y,z,phi, theta)→[abs(1-sin(10*phi)),abs(sin(10*phi)),0]:
a := 1..3:
b := 3:
Shell := plot::Spherical( [(a^phi)*sin(b*t),phi,t], phi = -1..2*PI, t = 0..PI, Mesh = [50,50],
FillColorFunction = h):
MyCam := plot::Camera([100,70,50],[0,0,-0.5], PI/45):
plot( Shell, MyCam, Scaling = Constrained, Axes = None)

```



9 Implicit3d

```

Steiner := plot::Implicit3d(
    y^2*z^2 + z^2*x^2 + x^2*y^2 + 2*x*y*z = 0,
    x=-1..1, y=-1..1, z=-1..1,
    MeshVisible=TRUE,
    XMesh=25, YMesh=25, ZMesh=25
):
plot(Steiner, Axes=None, Scaling=Constrained)

```



C1 := (u,v,x,y,z) -> [abs(x),abs(y),abs(z)]:

```

SteinerParam:=plot::Surface(
    [sin(2*u)*(cos(v))^2,
     sin(u)*sin(2*v),
     cos(u)*sin(2*v)],
    u=-PI/2..PI/2,
    v=-PI/2..PI/2,
    FillColorFunction=C1,
    Scaling=Constrained,
    UMesh=50,
    VMesh=50
):
plot(SteinerParam, Axes=None)
Error: An arithmetical expression is expected. [sin]

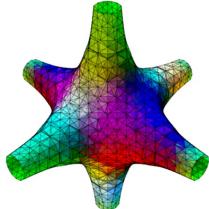
```

Kummer's surface

```

Kummer := x^2*y^2 + y^2*z^2 + z^2*x^2 - 1:
KummerColor := (x,y,z) -> [max(0,sin(2*x)), max(0,cos(2*y)), max(0,sin(2*z))]:
KummerSurf := plot::Implicit3d( Kummer, x = -3..3, y = -3..3, z = -3..3, Mesh = [20,20,20], FillColorFunction =
KummerColor, MeshVisible = TRUE):
MyCam := plot::Camera([10,10,10],[0,0,0.3],PI/10):
plot(KummerSurf, MyCam, Scaling = Constrained, Axes = None)

```



10 Spherical coordinates

```

p := x -> abs(5*x - trunc(5*x)):
Cl := (u,v,x,y,z)->[p(x*y),p(y*z),p(z*x)]:
Shell := plot::Spherical(
    [u*v,u,v],u=0..2*PI,v=0..PI,
    FillColorFunction=Cl
):
plot(
    Shell,
    Axes=Origin,
    AxesLineWidth=0.7,
    AxesTips=TRUE
)
Error: The argument '((x, y, z) -> (x - 1)^2 + (y - 1)^2 + (z - 1)^2) = 0..2*PI' is unexpected. [plot::Spherical::new]

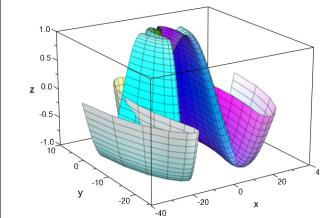
```

11 Cylindrical coordinates

```

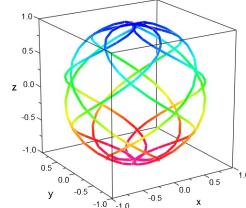
Cl2:= (u,z) -> [abs(1-z/PI) ,abs(1-u/PI),abs(u/PI)]:
Hat := plot::Cylindrical(
    [t*v, sin(t), sin(v)],
    t=-2*PI..2*PI, v=0..2*PI,
    Scaling=Unconstrained,
    FillColorFunction=Cl2,
    UMesh=50,
    VMesh=50
):
plot(Hat)

```

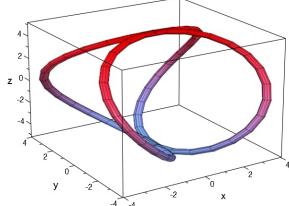


12 Curve3d and Tube

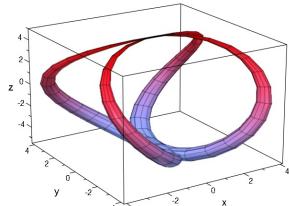
```
a := 5: b := 7: r := 1:
x := t -> r*sin(a*t)*cos(b*t):
y := t -> r*sin(a*t)*sin(b*t):
z := t -> r*cos(a*t):
C3D := plot::Curve3d([x(t),y(t),z(t)], t=0..2*PI, Mesh=200, LineWidth=0.8, LineColorType=Rainbow):
plot(C3D, Scaling = Constrained)
```



```
a := 7:
b := 3.5:
r := 5:
x := t -> r*sin(a*t)*cos(b*t):
y := t -> r*sin(a*t)*sin(b*t):
z := t -> r*cos(a*t):
T3D := plot::Tube([x(t),y(t),z(t)], 0.2, t=0..2*PI/b):
plot(T3D, Scaling=Unconstrained)
```



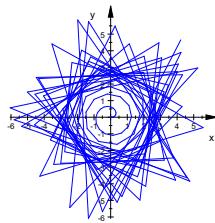
```
a := 7:
b := 3.5:
r := 5:
x := t -> r*sin(a*t)*cos(b*t):
y := t -> r*sin(a*t)*sin(b*t):
z := t -> r*cos(a*t):
T3D := plot::Tube([x(t),y(t),z(t)], sin(t*b)/2, t=0..2*PI/b):
plot(T3D, Scaling=Unconstrained)
```



Refinement

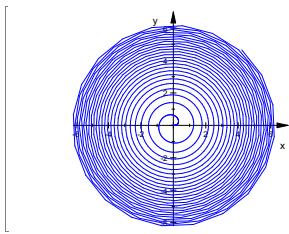
In some cases, the default of 121 evaluations on the curve is not sufficient and causes visible artifacts:

```
[reset():
plot(plot::Polar([r, 4*r^2], r = 0..2*PI))
```



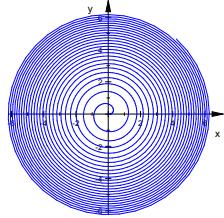
One remedy for this problem is to increase the number of evaluation points:

```
[plot(plot::Polar([r, 4*r^2], r = 0..2*PI, Mesh = 1000))]
```



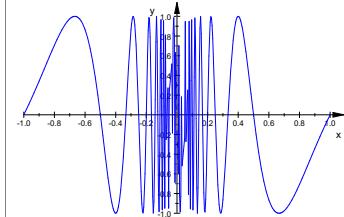
This method is, however, wasteful: Near the center, the initial density was perfectly sufficient, while on the outer edge still more points would be desirable. `plot::Polar` offers `adaptive mesh refinement` for exactly these situations. In the following example, we switch on adaptive mesh refinement with up to $2^4 = 16$ points introduced between each two consecutive points of the initial mesh:

```
plot(plot::Polar([r, 4*r^2], r = 0..2*PI, AdaptiveMesh=4))
```



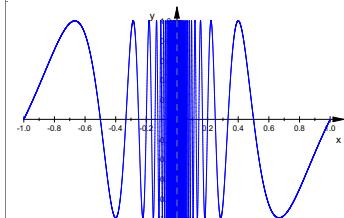
The standard mesh for the numerical evaluation of a function graph does not suffice to generate a satisfying graphics in the following case:

```
plot(plot::Function2d(sin(PI/x), x = -1 .. 1));
```



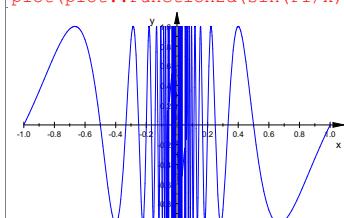
We increase the number of mesh points:

```
plot(plot::Function2d(sin(PI/x), x = -1 .. 1, XMesh = 10000));
```



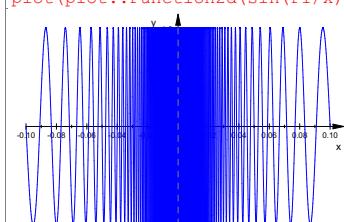
Alternatively, we enable adaptive sampling by setting `AdaptiveMesh` to some positive value:

```
plot(plot::Function2d(sin(PI/x), x = -1 .. 1, AdaptiveMesh = 10));
```



Finally, we increase the `XMesh` value and use adaptive sampling:

```
plot(plot::Function2d(sin(PI/x), x = -0.1 .. 0.1, XMesh = 1000, AdaptiveMesh = 10));
```



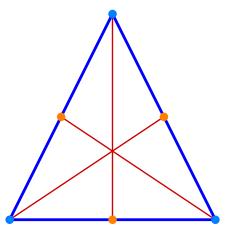
Plotting geometry models - Points, lines and polygons

```
// point coordinates
x1 := -1: x2 := 1: x3 := 0:
y1 := -1: y2 := -1: y3 := 1:
// declarations of 2D points
point1 := plot::Point2d([x1,y1]):
```

```

point2 := plot::Point2d([x2,y2]):
point3 := plot::Point2d([x3,y3]):
points := plot::Group2d(
    point1, point2, point3,
    PointColor=[0,0.5,1],
    PointSize = 3*unit::mm
):
// sides of the triangle
side1 := plot::Line2d([x1,y1],[x2,y2]):
side2 := plot::Line2d([x2,y2],[x3,y3]):
side3 := plot::Line2d([x3,y3],[x1,y1]):
sides := plot::Group2d(
    side1, side2, side3, LineWidth=1
):
// midpoints of sides
midpoint1 := plot::Point2d([(x1+x2)/2,(y1+y2)/2]):
midpoint2 := plot::Point2d([(x2+x3)/2,(y2+y3)/2]):
midpoint3 := plot::Point2d([(x1+x3)/2,(y1+y3)/2]):
midpoints := plot::Group2d(
    midpoint1, midpoint2, midpoint3,
    PointColor=[1,0.5,0],
    PointSize = 3*unit::mm
):
// medians
median1 := plot::Line2d([x1,y1],[(x2+x3)/2,(y2+y3)/2]):
median2 := plot::Line2d([x2,y2],[(x1+x3)/2,(y1+y3)/2]):
median3 := plot::Line2d([x3,y3],[(x1+x2)/2,(y1+y2)/2]):
medians := plot::Group2d(
    median1, median2, median3,
    LineColor=[0.8,0,0],
    LineWidth=0.5
):
plot(sides, medians, midpoints,points,
    Scaling=Constrained,
    Axes=None
)

```

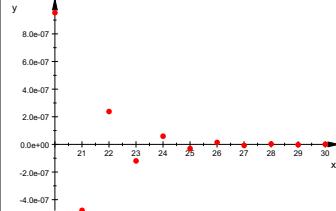


Points

```

// here we declare our sequence
data := [[n,1/(-2)^n] $ n=20..30]:
// now we declare plot object for the sequence
sequence := plot::PointList2d(data,
    PointSize=2*unit::mm,
    PointColor=RGB::Red
):
plot(sequence)

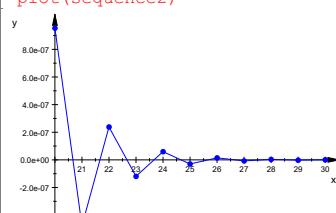
```



```

sequence2 := plot::Polygon2d(data,
    PointSize=2,
    PointsVisible=TRUE
):
plot(sequence2)

```



Solids in MuPAD

```

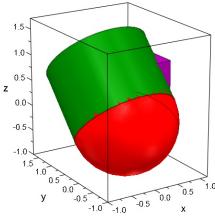
// declarations of four solids
RedSphere := plot::Sphere(1,[0,0,0],
    FillColor=[1,0,0]
):

```

```

GreenCylinder := plot::Cylinder(1,[0,0,0],[0,1,1],
  FillColor=[0,0.5,0]
):
PinkBox := plot::Box([0,0,0], [1,1,1],
  FillColor=[0.6, 0, 0.6]
):
BlueCone := plot::Cone(1,[0,0,0], 0.2,[1,1,1]):
plot(RedSphere, GreenCylinder, BlueCone, PinkBox)

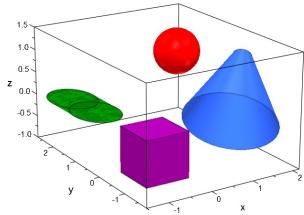
```



```

// transformations
A:=plot::Translate3d([1,1,1],
  plot::Scale3d([0.5,0.5,0.5],RedSphere)
):
B:=plot::Translate3d([-1,1,0],
  plot::Scale3d([0.5,1,0],GreenCylinder)
):
C:=plot::Translate3d([-1,-1,-1],PinkBox):
S:=plot::Translate3d([1,-1,0],BlueCone):
// finally we plot translated solids
plot(A,B,C,S)

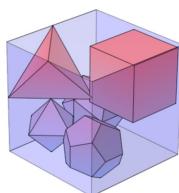
```



```

Bo := plot::Box([0,0,0],[4,4,4],
  FillColor=[0.7, 0.7, 1, 0.6]
):
He := plot::Hexahedron (
  Center = [2.9, 2.9, 2.9],
  Radius = 1
):
Te := plot::Tetrahedron (
  Center = [1, 1, 3],
  Radius = 1
):
Oc := plot::Octahedron (
  Center = [1, 1, 1],
  Radius = 1
):
Ic := plot::Icosahedron (
  Center = [1, 3, 1],
  Radius = 1
):
Do := plot::Dodecahedron(
  Center = [3, 1, 1],
  Radius = 1
):
Cam := plot::Camera(
  [28,-23,20],[1.5,1.5,1.5], PI/18
):
plot(Bo, He, Te, Oc, Ic, Do, Cam, Axes=None)

```

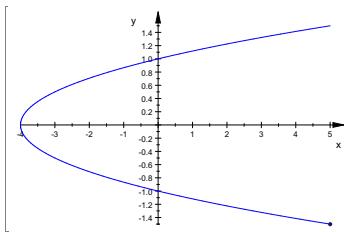


Animation step-by-step

```

reset():
Curve := plot::Curve2d([t^2-4, t/2], t=-3..3):
Particle := plot::Point2d([a^2-4, a/2], a=-3..3):
plot(Curve, Particle)

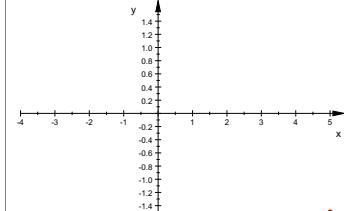
```



```

Curve := plot::Curve2d([t^2-4, t/2], t=-3..a, a=-3..3):
Particle := plot::Point2d([a^2-4, a/2], a=-3..3,
  PointSize=2,
  PointColor=RGB::Red
):
plot(Curve, Particle)

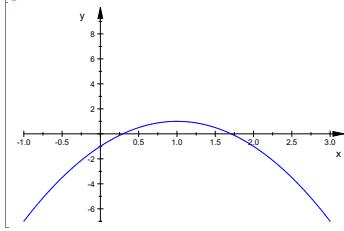
```



```

h := 1:
k := 1:
Parabola := plot::Function2d(
  a*(x-h)^2+k, x=-1..3, a=-2..2
):
plot(Parabola)

```



```

// radii of both circles
r := 0.5:
R := 2:

// coordinates of the particle
coordinates :=
  [(R-r)*cos(phi)+r*cos(((R-r)/r)*phi),
   (R-r)*sin(phi)-r*sin(((R-r)/r)*phi)]:

```

```

// static objects
LargeCircle := plot::Circle2d(R,
  LineColor=RGB::Black
):

```

```

// objects to animate
SmallCircle:= plot::Circle2d(
  r, [(R-r)*cos(a), (R-r)*sin(a)],
  a=0..2*PI,
  Color = [0.8,0,0],
  LineColor=RGB::Black,
  LineWidth=0.1,
  Filled=TRUE,
  FillPattern=Solid
):

```

```

Particle:=plot::Point2d(
  coordinates,
  phi = 0..2*PI,
  PointSize = 2,
  PointColor = [0,0,1]
):

```

```

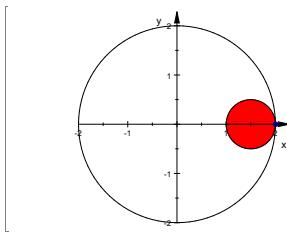
Curve := plot::Curve2d(
  coordinates,
  phi =0..a, a=0..2*PI
):
// now we plot all together

```

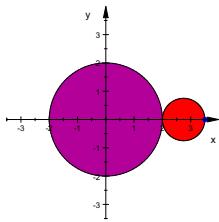
```

plot(LargeCircle, SmallCircle, Particle, Curve,
  Frames=80,
  Scaling=Constrained,
  AxesInFront=TRUE
)

```



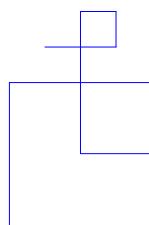
```
// define radius
r := 0.75:
R := 2:
// position of drawing point
Middle := [
  [(R+r)*cos(phi)+r*cos((1+R/r)*phi),
   (R+r)*sin(phi)+r*sin((1+R/r)*phi)]:
BigCircle := plot::Circle2d(R,
  LineColor=RGB::Black,
  Filled=TRUE,
  FillColor=[0.7,0,0.6],
  FillPattern=Solid
):
SmallCircle:= plot::Circle2d(
  r, [(R+r)*cos(phi), (R+r)*sin(phi)],
  phi=0..6*PI,
  Color = [0.8,0,0],
  LineColor=RGB::Black,
  LineWidth=0.1,
  Filled=TRUE,
  FillPattern=Solid
):
Point:=plot::Point2d(
  Middle,
  phi = 0..6*PI,
  PointSize = 2,
  PointColor = [0,0,1]
):
Curve := plot::Curve2d(
  Middle,
  phi = 0..a, a=0..6*PI
):
// plotting all together
plot(BigCircle, SmallCircle, Point, Curve,
  Frames=100,
  Scaling=Constrained,
  AxesInFront=TRUE
)
```

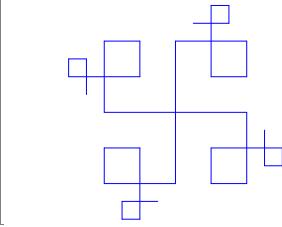


Turtle graphics and L-systems

```
T:=plot::Turtle():
T::forward(100): T::right(PI/2):
T::forward(100): T::right(PI/2):
T::forward(50): T::right(PI/2):
T::forward(50): T::right(PI/2):
T::forward(100): T::right(PI/2):
T::forward(25): T::right(PI/2):
T::forward(25): T::right(PI/2):
T::forward(50):
plot(T)

T2 := plot::Rotate2d(PI/2,[0,0],T):
T3 := plot::Rotate2d(PI,[0,0],T):
T4 := plot::Rotate2d(3*PI/2,[0,0],T):
plot(T,T2,T3,T4)
```

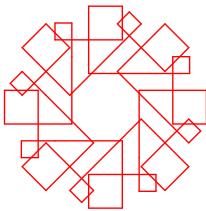




```

A1 := plot::Translate2d([50,-75], T):
A2 := plot::Rotate2d( PI/4,[0,0],A1):
A3 := plot::Rotate2d(2*PI/4,[0,0],A1):
A4 := plot::Rotate2d(3*PI/4,[0,0],A1):
A5 := plot::Rotate2d(4*PI/4,[0,0],A1):
A6 := plot::Rotate2d(5*PI/4,[0,0],A1):
A7 := plot::Rotate2d(6*PI/4,[0,0],A1):
A8 := plot::Rotate2d(7*PI/4,[0,0],A1):
plot(A1,A2,A3,A4,A5,A6,A7,A8,
    LineColor=RGB::Red,
    LineWidth=0.5
)

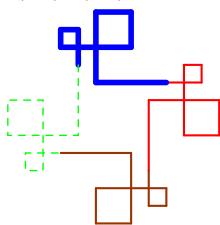
```



```

A1 := plot::modify(T, LineColor=RGB::Red):
A1 := plot::Translate2d([50,-75], A1):
A3 := plot::modify(T, LineColor=RGB::Blue, LineWidth=2):
A3 := plot::Translate2d([50,-75], A3):
A3 := plot::Rotate2d(2*PI/4,[0,0],A3):
A5 := plot::modify(T,
    LineColor=RGB::Green,
    LineStyle=Dashed,
    LineWidth=0.5
):
A5 := plot::Translate2d([50,-75], A5):
A5 := plot::Rotate2d(4*PI/4,[0,0],A5):
A7 := plot::modify(T, LineColor=RGB::Brown):
A7 := plot::Translate2d([50,-75], A7):
A7 := plot::Rotate2d(6*PI/4,[0,0],A7):
plot(A1,A3,A5,A7, LineWidth=0.75)

```

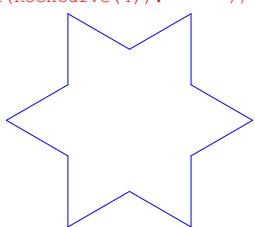


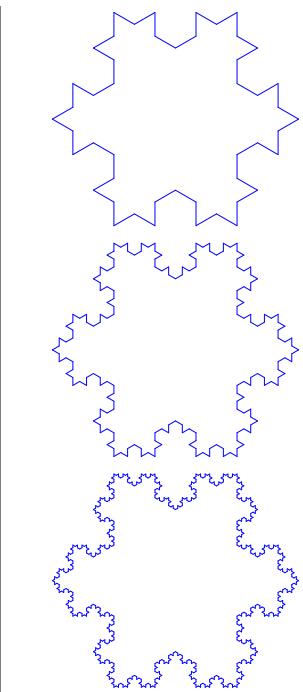
Lindenmayer systems

```

KochCurve := proc(n)
begin
    plot::Lsys( // start a new L-system
        PI/3,           // turtle must always turn PI/3
        "F++F++F",     // this is the seed
        "F"="F-F++F-F", // iteration rule
        Generations=n   // number of generations
    );
end;
plot(KochCurve(1));      // now plot the turtle path
plot(KochCurve(2));      // now plot the turtle path
plot(KochCurve(3));      // now plot the turtle path
plot(KochCurve(4));      // now plot the turtle path

```





```
plot(plot::Lsys(PI/9, "BL", "L" = "BR[+HL]BR[-GL]+HL",
               "R" = "RR", "L" = Line, "R" = Line,
               "B" = RGB::Brown, "H" = RGB::ForestGreen,
               "G" = RGB::SpringGreen, Generations = 6)):
```



```
plot(plot::Lsys(PI/3, "R", "L" = "R+L+R", "R" = "L-R-L",
               "L" = Line, "R" = Line,
               Generations = 7)):
```

