

An Introduction to Linear Algebra

```

Info (linalg)
Library 'linalg': the linear algebra package

-- Interface
linalg::addCol,      linalg::addRow,      linalg::adjoint,
linalg::angle,      linalg::basis,      linalg::barnard,
linalg::changepoly, linalg::cont,      linalg::companion,
linalg::concatMatrix, linalg::cond,      linalg::crossProduct,
linalg::curl,      linalg::detCol,      linalg::detRow,
linalg::det,      linalg::divergence, linalg::eigenvalues,
linalg::eigenVectors, linalg::exprMatrix, linalg::factorCholesky,
linalg::factorID, linalg::factorQR, linalg::frobeniusForm,
linalg::gaussElim, linalg::gaussJordan, linalg::grad,
linalg::gradient, linalg::hermiteForm, linalg::heisenberg,
linalg::hessian, linalg::hilbert, linalg::intranspose,
linalg::inBasis, linalg::inverseLU, linalg::inWihbert,
linalg::invpascal, linalg::invvandermonde, linalg::isHermitian,
linalg::isPosDef, linalg::isUnitary, linalg::jacobian,
linalg::jordanForm, linalg::kronckerProduct, linalg::lagrangian,
linalg::lmarin, linalg::matInsolve, linalg::matInsolveLU,
linalg::matpoly, linalg::matCol, linalg::multRow,
linalg::ncols, linalg::nonZero, linalg::normalize,
linalg::norm, linalg::nmlapace, linalg::ogcoorTab,
linalg::orthog, linalg::pascal, linalg::permanent,
linalg::potential, linalg::psuedoInverse, linalg::randomMatrix,
linalg::rank, linalg::row, linalg::scalarProduct,
linalg::setCol, linalg::setRow, linalg::smithForm,
linalg::sortMatrix, linalg::sqrMatrix, linalg::subMatrix,
linalg::substitute, linalg::sumBasis, linalg::swapCol,
linalg::swapRow, linalg::syWester, linalg::teplitz,
linalg::tripletsolve, linalg::trif, linalg::transpose,
linalg::vandermonde, linalg::vandermondeSolve, linalg::vecdim,
linalg::vectorCR, linalg::vectorPotential, linalg::weidemann,

```

Systems of linear equations

```

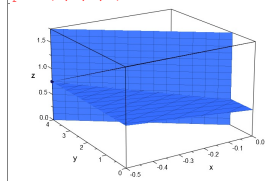
reset():
equations := {
  x - 2*y - 3*z + t = 7,
  x + y + z + t = 1,
  5*x - 3*y - 3*z = 2
}
[5x-3y-3z=2,t+x-2y-3z=7,t+x+y+z=1]
solve(equations, {x,y,z})
[[x = 5/8, y = 3/8, z = 1/8, t = 15/8]]
linsolve(equations, {x,y,z})
[x = 5/8, y = 3/8, z = 1/8, t = 15/8]
linsolve(equations, [z,y,x])
[z = 1/8, y = 3/8, x = 15/8]
linsolve(
  {5*cos(x)+3*exp(x) = 1, cos(x)-2*exp(x) = 0},
  {cos(x), exp(x)}
)
[cos(x) = 2/11, e^x = 1/11]
linsolve({5*x+3*y = 1, -2*x - 5*y = 0}, {x,y},
  Domain = Dom::IntegerMod(7)
)
[x = 1 mod 7, y = 1 mod 7]

```

```

eq1 := x + 2*z = 1;
eq2 := y + 4*z = 7;
eq3 := 6*x + y = 1;
linsolve({eq1,eq2,eq3}, {x,y,z})
[x = -1/2, y = 4, z = 3/2]
// finding a point on each plane
solve(subs(eq1, x=0, y=0), z)
[[3/2]]
solve(subs(eq2, x=0, y=0), z)
[[7/4]]
solve(subs(eq3, x=0, z=0), y)
[[1]]
// declare planes and the point
A := plot::Plane([0,0,1/2],[1,0,2]);
B := plot::Plane([0,0,7/4],[0,1,4]);
C := plot::Plane([0,1,0],[6,1,0]);
P := plot::Point3d([-1/2,4,3/4]);
plot(A,B,C,P)

```



```

eq1 := x + 3*y + 2*z = 1;
eq2 := 2*x + 6*y + 4*z = 7;
eq3 := -x - 3*y - 2*z = 3;
linsolve({eq1,eq2,eq3}, {x,y,z})
FAIL

```

Declarations of matrices

```

matrix(3, 3, [[0,1,2], [1,0,3], [4,5,0]])
[[0 1 2]
 [1 0 3]
 [4 5 0]]
matrix(4, 4, [[0,1,2], [1,0,3], [4,5,0]])
[[0 1 2 0]
 [1 0 3 0]
 [4 5 0 0]
 [0 0 0 0]]
matrix(4, 3, [[0,1,2], [1,0,3], [4,5,0]])
[[0 1 2]
 [1 0 3]
 [4 5 0]
 [0 0 0]]
matrix::identity(4)
[[1 0 0 0]
 [0 1 0 0]
 [0 0 1 0]
 [0 0 0 1]]
matrix(4, 5, [5,3,2,5,8], Diagonal)
[[5 0 0 0]
 [0 3 0 0]
 [0 0 2 0]
 [0 0 0 5]]
matrix(5, 5, [1,2,3,4,5,6,7,8,9], Banded)
[[5 6 7 8 9]
 [1 2 3 4 5]
 [1 2 3 4 5]
 [1 2 3 4 5]
 [1 2 3 4 5]]

```

```

matrix(5, 5, [5,3,3,5,8], Banded)

$$\begin{pmatrix} 3 & 5 & 8 & 0 & 0 \\ 5 & 3 & 3 & 8 & 0 \\ 3 & 3 & 3 & 8 & 0 \\ 0 & 0 & 3 & 3 & 5 \end{pmatrix}$$

matrix(4, 4, (n,m) -> exp(n + m))

$$\begin{pmatrix} e^5 & e^6 & e^7 & e^8 \\ e^6 & e^7 & e^8 & e^9 \\ e^7 & e^8 & e^9 & e^{10} \\ e^8 & e^9 & e^{10} & e^{11} \end{pmatrix}$$

matrix(4, 4, n -> exp(n), Diagonal)

$$\begin{pmatrix} e & 0 & 0 & 0 \\ 0 & e^2 & 0 & 0 \\ 0 & 0 & e^4 & 0 \\ 0 & 0 & 0 & e^8 \end{pmatrix}$$

linalg::hilbert(5)

$$\begin{pmatrix} 1 & \frac{1}{2} & \frac{1}{3} & \frac{1}{4} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{3} & \frac{1}{4} & \frac{1}{5} & \frac{1}{6} \\ \frac{1}{3} & \frac{1}{4} & \frac{1}{5} & \frac{1}{6} & \frac{1}{7} \\ \frac{1}{4} & \frac{1}{5} & \frac{1}{6} & \frac{1}{7} & \frac{1}{8} \\ \frac{1}{5} & \frac{1}{6} & \frac{1}{7} & \frac{1}{8} & \frac{1}{9} \end{pmatrix}$$

linalg::randomMatrix(5, 5, Dom::Integer)

$$\begin{pmatrix} 824 & -65 & -814 & -741 & -979 \\ -764 & 216 & -663 & 880 & 916 \\ 617 & -535 & 597 & -245 & 79 \\ 747 & 477 & -535 & -906 & -905 \\ -266 & -8 & 765 & 448 & -348 \end{pmatrix}$$

linalg::randomMatrix(4, 4, Dom::Integer, 0..9)

$$\begin{pmatrix} 1 & 4 & 6 & 3 \\ 2 & 1 & 3 & 9 \\ 1 & 8 & 1 & 0 \\ 4 & 1 & 9 & \end{pmatrix}$$

linalg::randomMatrix(6, 6, Dom::Integer, 0..100, Diagonal)

$$\begin{pmatrix} 15 & 0 & 0 & 0 & 0 & 0 \\ 0 & 24 & 0 & 0 & 0 & 0 \\ 0 & 0 & 58 & 0 & 0 & 0 \\ 0 & 0 & 0 & 63 & 0 & 0 \\ 0 & 0 & 0 & 0 & 21 & 0 \\ 0 & 0 & 0 & 0 & 0 & 36 \end{pmatrix}$$


```

Visualization of matrices

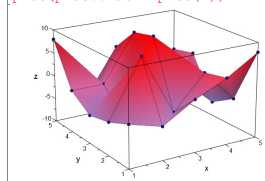
```

B := linalg::randomMatrix(5,5, Dom::Integer, -10..10)

$$\begin{pmatrix} -1 & -3 & 1 & 4 & 8 \\ -3 & 9 & -4 & 3 & -4 \\ -4 & -6 & 10 & -1 & -7 \\ -1 & -1 & 9 & -7 & 2 \\ 8 & -6 & 4 & -10 & 1 \end{pmatrix}$$

plot(plot::Matrixplot(B))

```



Operations on matrices

```

A := matrix(3,3, [[7,6,0],[8,0,3],[6,1,9]]);
B := matrix(3,3, [[9,7,0],[0,6,1],[0,0,8]]);
C := matrix(2,3, [[7,1,7],[0,8,4]]);
F := matrix(3,2, [[1,8],[7,5],[7,0]]);

```

```


$$\begin{pmatrix} 7 & 6 & 0 \\ 8 & 0 & 3 \\ 6 & 1 & 9 \end{pmatrix}$$


$$\begin{pmatrix} 9 & 7 & 0 \\ 0 & 6 & 1 \\ 0 & 0 & 8 \end{pmatrix}$$


$$\begin{pmatrix} 7 & 1 & 7 \\ 0 & 8 & 4 \end{pmatrix}$$


$$\begin{pmatrix} 1 & 8 \\ 7 & 0 \end{pmatrix}$$


```

```
A + B
```

```

$$\begin{pmatrix} 16 & 13 & 0 \\ 8 & 6 & 4 \\ 6 & 1 & 17 \end{pmatrix}$$

```

```
3*A + 5*B
```

```

$$\begin{pmatrix} 66 & 53 & 0 \\ 24 & 30 & 14 \\ 18 & 3 & 67 \end{pmatrix}$$

```

```
A*B // this operation can be done
```

```

$$\begin{pmatrix} 63 & 85 & 6 \\ 72 & 56 & 24 \\ 54 & 48 & 73 \end{pmatrix}$$

```

```
B*F // this operations can be done also
```

```

$$\begin{pmatrix} 58 & 107 \\ 49 & 30 \\ 56 & 0 \end{pmatrix}$$

```

```
F*B // this operations cannot be done
```

Error: The dimensions do not match. ([Dom:Matrix(Dom:ExpressionField())]:_mul2)

```
A^(-1)
```

```

$$\begin{pmatrix} \frac{1}{11} & \frac{18}{11} & -\frac{6}{11} \\ \frac{18}{11} & -\frac{21}{11} & \frac{11}{11} \\ -\frac{18}{11} & \frac{11}{11} & \frac{11}{11} \end{pmatrix}$$

```

```
Float(A^(-1))
```

```

$$\begin{pmatrix} 0.0909090909090909 & 1.636363636363636 & -0.545454545454545 \\ 1.636363636363636 & -1.909090909090909 & 1.000000000000000 \\ -1.636363636363636 & 1.000000000000000 & 1.000000000000000 \end{pmatrix}$$

```

```
linalg::transpose(A)
```

```

$$\begin{pmatrix} 7 & 8 & 6 \\ 6 & 0 & 1 \\ 0 & 3 & 9 \end{pmatrix}$$

```

```
g := x -> x*exp(-x^3);
```

```
x -> x e-3x
```

```
A := matrix([[7,6,0],[8,0,3],[6,1,9]]);
```

```
map(A, g) //apply a function to all operands of an object
```

```

$$\begin{pmatrix} 7e^{-21} & 6e^{-18} & 0 \\ 8e^{-24} & 0 & 3e^{-9} \\ 6e^{-18} & e^{-3} & 9e^{-27} \end{pmatrix}$$

```

```
map(A, x -> x*exp(-x^3))
```

```

$$\begin{pmatrix} 7e^{-21} & 6e^{-18} & 0 \\ 8e^{-24} & 0 & 3e^{-9} \\ 6e^{-18} & e^{-3} & 9e^{-27} \end{pmatrix}$$

```

```
f := (x,y) -> x*y;
```

```
zip(A,B,f)
```

```

$$\begin{pmatrix} 63 & 42 & 0 \\ 0 & 0 & 3 \\ 0 & 0 & 72 \end{pmatrix}$$

```

```
f := (x,y)->max(x,y):
zip(A,B,f)

$$\begin{pmatrix} 9 & 7 & 0 \\ 8 & 6 & 3 \\ 6 & 1 & 9 \end{pmatrix}$$

g := (x,y)->min(x,y):
zip(A,B,g)

$$\begin{pmatrix} 7 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 8 \end{pmatrix}$$

```

```
h := (n,m) -> gcd(n,m):
zip(A,B,h)

$$\begin{pmatrix} 1 & 1 & 0 \\ 8 & 6 & 1 \\ 6 & 1 & 1 \end{pmatrix}$$

```

```
A := matrix(3,3,[[3, 2, 5],[-1, 5, 3],[1, 2, -5]])

$$\begin{pmatrix} 3 & 2 & 5 \\ -1 & 5 & 3 \\ 1 & 2 & -5 \end{pmatrix}$$

linalg::det(A)
-132
```

Solving systems of linear equations in matrix form

```
equations := [7*x+6*y = 1, 8*x+3*z = 2, 6*x+y+3*z = 3]
[7x+6y=1,8x+3z=2,6x+y+3z=3]
```

```
AM := linalg::expr2Matrix(equations, [x,y,z])
```

```

$$\begin{pmatrix} 7 & 6 & 0 & 1 \\ 8 & 0 & 3 & 2 \\ 6 & 1 & 3 & 3 \end{pmatrix}$$

```

```
B := linalg::col(AM,4)
```

```

$$\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$

```

```
A := linalg::delCol(AM,4)
```

```

$$\begin{pmatrix} 7 & 6 & 0 \\ 8 & 0 & 3 \\ 6 & 1 & 3 \end{pmatrix}$$

```

```
linalg::matlinsolve(A,B)
```

```

$$\begin{pmatrix} -\frac{1}{10} \\ \frac{5}{10} \\ \frac{9}{10} \end{pmatrix}$$

```

```
solve(equations, {x,y,z})
```

```
[[x=-1/10,y=5/10,z=9/10]]
```

Gaussian elimination

```
reset():
```

```
A := Dom::Matrix(Dom::Integer)([[3, 2, 5, 4], [-1, 5, 3, -1], [1, 2, -5, 0]]);
B := Dom::Matrix(Dom::Rational)([[3, 2, 5, 4], [-1, 5, 3, -1], [1, 2, -5, 0]]);
C := Dom::Matrix(Dom::Float)([[3, 2, 5, 4], [-1, 5, 3, -1], [1, 2, -5, 0]])
```

```

$$\begin{pmatrix} 3 & 2 & 5 & 4 \\ -1 & 5 & 3 & -1 \\ 1 & 2 & -5 & 0 \end{pmatrix}$$

```

```

$$\begin{pmatrix} 3 & 2 & 5 & 4 \\ -1 & 5 & 3 & -1 \\ 1 & 2 & -5 & 0 \end{pmatrix}$$

```

```

$$\begin{pmatrix} 3.0 & 2.0 & 5.0 & 4.0 \\ -1.0 & 5.0 & 3.0 & -1.0 \\ 1.0 & 2.0 & -5.0 & 0.0 \end{pmatrix}$$

```

```
linalg::rank(A);
```

```
linalg::rank(B);
```

```
linalg::rank(C);
```

```
3
```

```
3
```

```
3
```

```
linalg::gaussElim(A);
```

```
linalg::gaussElim(B);
```

```
linalg::gaussElim(C)
```

```

$$\begin{pmatrix} 3 & 2 & 5 & 4 \\ 0 & 7 & 14 & 4 \\ 0 & 0 & -132 & -24 \end{pmatrix}$$

```

```

$$\begin{pmatrix} 3 & 2 & 5 & 4 \\ 0 & 7 & 14 & 4 \\ 0 & 0 & -132 & -24 \end{pmatrix}$$

```

```

$$\begin{pmatrix} 3.0 & 2.0 & 5.0 & 4.0 \\ 0.0 & 7.0 & 14.0 & 4.0 \\ 0.0 & 0.0 & -132.0 & -24.0 \end{pmatrix}$$

```

```
use(linalg, addRow, swapRow, multRow):
```

```
A := matrix( 3, 4, [[3, 2, 5, 4],[-1, 5, 3, -1],[1, 2, -5, 0]])
```

```

$$\begin{pmatrix} 3 & 2 & 5 & 4 \\ -1 & 5 & 3 & -1 \\ 1 & 2 & -5 & 0 \end{pmatrix}$$

```

```
addRow(A, 3, 2, 1) // addRow(A, r1, r2, s1) adds s1 times row r1 to row r2, in the matrix A.
```

```

$$\begin{pmatrix} 3 & 2 & 5 & 4 \\ 0 & 7 & -2 & -1 \\ 1 & 2 & -5 & 0 \end{pmatrix}$$

```

```
addRow(% , 3, 1, -3)
```

```

$$\begin{pmatrix} 0 & -4 & 20 & 4 \\ 0 & 7 & -2 & -1 \\ 1 & 2 & -5 & 0 \end{pmatrix}$$

```

```
swapRow(% , 1, 3)
```

```

$$\begin{pmatrix} 1 & 2 & -5 & 0 \\ 0 & 7 & -2 & -1 \\ 0 & -4 & 20 & 4 \end{pmatrix}$$

```

```
multRow(% , 3, 1/4)
```

```

$$\begin{pmatrix} 1 & 2 & -5 & 0 \\ 0 & 7 & -2 & -1 \\ 0 & -1 & 5 & 1 \end{pmatrix}$$

```

```
addRow(% , 3, 2, 7)
```

```

$$\begin{pmatrix} 1 & 2 & -5 & 0 \\ 0 & 0 & 33 & 6 \\ 0 & -1 & 5 & 1 \end{pmatrix}$$

```

```
swapRow(% , 2, 3)
```

```

$$\begin{pmatrix} 1 & 2 & -5 & 0 \\ 0 & -1 & 5 & 1 \\ 0 & 0 & 33 & 6 \end{pmatrix}$$

```

```
multRow(% , 2, -1) // remove -1
```

```

$$\begin{pmatrix} 1 & 2 & -5 & 0 \\ 0 & 1 & -5 & -1 \\ 0 & 0 & 33 & 6 \end{pmatrix}$$

```

```
multRow(% , 3, 1/33) // remove 33
```

```

$$\begin{pmatrix} 1 & 2 & -5 & 0 \\ 0 & 1 & -5 & -1 \\ 0 & 0 & 1 & 2/11 \end{pmatrix}$$

```

Minor expansion

```
reset():
```

```
use(linalg, nrows, ncols, delRow, delCol):
```

```
A := matrix([[3,2,5], [-1,5,3], [1,2,-5]])
```

```

$$\begin{pmatrix} 3 & 2 & 5 \\ -1 & 5 & 3 \\ 1 & 2 & -5 \end{pmatrix}$$

```

```

minor := proc(A, i, j)
begin
  B := delRow(A,i);
  B := delCol(B,j);
  return(hold(Det)(B))
end;
Det := proc(A)
local r, j;
begin
  r := 0;
  if (nrows(A) <> ncols(A)) then
    error("Wrong input matrix")
  else
    if nrows(A)=1 then
      return(A[1,1])
    else
      for j from 1 to ncols(A) do
        r:=r+(-1)^(1+j)*A[1,j]*minor(A,1,j)
      end;
    end;
  end;
  return(r)
end;
Det(A)
5Det((-1 5)
1 2)-2Det((-1 3)
1 -5)+3Det((5 3)
2 -5)
eval(%)
17 Det(-5)-14 Det(2)-19 Det(1)
eval(%)
-132
B := Dom::Matrix(Dom::Integer) ( [[3,2,5,4], [2,5,3,8], [1,2,3,0], [2,3,4,5]])
( 3 2 5 4
 2 5 3 8
 1 2 3 0
 2 3 4 5)
Det(B)
5Det((2 5 8)
1 2 3)-4Det((1 5 3)
1 2 4)-2Det((2 3 8)
1 4 5)+3Det((5 3 8)
3 4 5)
eval(%)
28 Det((1 3)
2 3)-19 Det((1 9)
2 9)+Det((3 9)
2 9)+4 Det((1 2)
2 2)+11 Det((1 4)
2 4)-16 Det((3 2)
2 2)
eval(%)
36 Det(4)-20 Det(3)-68 Det(2)+16 Det(5)
eval(%)
28

```

Angle

We compute the angle between the two vectors $\begin{pmatrix} 2 \\ 5 \end{pmatrix}$ and $\begin{pmatrix} -3 \\ 3 \end{pmatrix}$:

```

phi := linalg::angle(
  matrix([2, 5]), matrix([-3, 3])
)
arccos( sqrt(18)/sqrt(29) )

```

We give two further examples:

```

linalg::angle(
  matrix([1, -1]), matrix([1, 1])
)
pi/2
linalg::angle(
  matrix([1, 1]), matrix([-1, -1])
)
pi

```

Trace

```

A := Dom::Matrix(Dom::Integer)
(3, 3, (i, j) -> 3*(i - 1) + j)
( 4 3 6
 7 8 9)
linalg::tr(A)
15

```

Determinant

```

A := matrix([[a11, a12], [a21, a22]])
( a11 a12
  a21 a22)

```

which gives us the well-known formula for the determinant of an arbitrary 2×2 matrix:

```

linalg::det(A)
a11 a22 - a12 a21

```

The standard algorithms for computing determinants suffer from extreme internal expression swell when many symbolic entries are involved. For this reason, the following computation takes some time:

```

A := matrix([[x, y, z, x, y, z, 0, 0, 0],
             [0, x, y, z, x, y, z, 0, 0],
             [0, 0, x, y, z, x, y, z, 0],
             [0, 0, 0, x, y, z, x, y, z],
             [z, 0, 0, 0, x, y, z, x, y],
             [y, z, 0, 0, 0, x, y, z, x],
             [x, y, z, 0, 0, 0, x, y, z],
             [z, x, y, z, 0, 0, 0, x, y],
             [y, z, x, y, z, 0, 0, 0, x]
            ]);
t1 := time((d1 := linalg::det(A)))*msec;
t1, d1
218.4014 msec, 8 x^9 + 72 x^8 y^2 - 240 x^7 y^3 z^2 + 216 x^6 y^4 z^2 - 72 x^5 y^5 z + 8 y^6 + 8 z^6

```

Eigenvalues

We compute the eigenvalues of the matrix $A = \begin{pmatrix} 1 & 4 & 2 \\ 1 & 4 & 2 \\ 2 & 5 & 3 \end{pmatrix}$:

```

A := matrix([[1, 4, 2], [1, 4, 2], [2, 5, 3]]);
linalg::eigenvalues(A)
[0, 4 - sqrt(5), sqrt(5) + 4]

```

If we consider the matrix over the domain `Dom::Float`, then the call of `linalg::eigenvalues(A)` results in a numerical computation of the eigenvalues of `A` via `numeric::eigenvalues`:

```

B := Dom::Matrix(Dom::Float)(A);
linalg::eigenvalues(B)
[-1.370431546 10^-18, 0.1270166538, 7.872983346]

```

With the option `Multiple` we get the information about the algebraic multiplicity of each eigenvalue:

```

C := Dom::Matrix(Dom::Rational)(4, 4, [[-3], [0, 6]])

```

$$\begin{pmatrix} -3 & 0 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

```
linalg::eigenvalues(C, Multiple)
[[[-3, 1], [0, 2], [6, 1]]]
```

Eigenvectors

We compute the eigenvalues and the eigenvectors of the matrix $A = \begin{pmatrix} 1 & -3 & 3 \\ 6 & -10 & 6 \\ 6 & 6 & 4 \end{pmatrix}$:

```
A := Dom::Matrix(Dom::Rational) (
  [[1, -3, 3], [6, -10, 6], [6, 6, 4]]
);
Ev:= linalg::eigenvectors(A)
[[[-11, 1, [[(-11/10), (1/10)]]], [-2, 1, [[(-1/10), (1/10)]]], [8, 1, [[(1/10), (1/10)]]]]]
```

The matrix A is diagonalizable. Hence, we extract the eigenvectors and combine them to a matrix P such that $P^{-1} * A * P$ is the diagonal matrix whose diagonal entries are given by the corresponding eigenvalues:

```
Eigenvectors:= Ev[1][3][1], Ev[2][3][1], Ev[3][3][1]
[[(-11/10), (1/10), (1/10)]]
```

```
P:= Eigenvectors[1].Eigenvectors[2].Eigenvectors[3]
[[(-11/10, -1/10, 1/10)]]
```

```
P^-1 * A * P
[[(-11, 0, 0)]]
```

A more skillful way of extracting the above eigenvectors from the output generated by `linalg::eigenvectors` is the following:

```
map(Ev, op@op, 3)
[[(-11/10), (1/10), (1/10)]]
```

If we consider the matrix A over the domain `Dom::Float`, the call of `linalg::eigenvectors(A)` results in a numerical computation of the eigenvalues and the eigenvectors of A via the function `numeric::eigenvectors`:

```
B := Dom::Matrix(Dom::Float) (A);
linalg::eigenvectors(B)
[[[8.0, 1, [[(0.2248595062), (0.3271705844)]]], [-2.0, 1, [[(0.7071067812), (0.7071067812)]]], [-11.0, 1, [[(0.3218603429), (0.3271409818)]]]]]
```

Characteristic polynomial

We define a matrix over the rational numbers:

```
A := Dom::Matrix(Dom::Real) ([[1, 2], [3, 4]])
[[[1, 2], [3, 4]]]
```

Then the characteristic polynomial $p_A(x)$ is given by:

```
linalg::charpoly(A, x)
x^2 - 5x + 2
B := matrix(3,3,[[1, 2, -1], [-1,-1,4],[3, 4, -5]])
[[[1, 2, -1], [-1, -1, 4], [3, 4, -5]]]
solve(linalg::charpoly(B, x), x)
[[2 - sqrt(41)/2, 2 + sqrt(41)/2]]
linalg::eigenvalues(B)
[[2 - sqrt(41)/2, 2 + sqrt(41)/2]]
```

Norm

```
M := matrix([[a, b], [c, d]]);
norm(M)=norm(M, Infinity);
norm(M, 1);
norm(M, 2)=norm(M, Spectral);
norm(M, Frobenius);
max(|a| + |b|, |c| + |d|) = max(|a| + |b|, |c| + |d|)
max(|a| + |c|, |b| + |d|)
sigma_1 = sigma_1
where
sigma_1 = sqrt(max(|a_1 + a_2 + a_3 + a_4 - a_5|, |a_1 + a_2 + a_3 + a_4|))
sigma_1 = sqrt((a^2 + b^2 + c^2 + d^2 + 2*|a*b| + 2*|a*c| + 2*|a*d| + 2*|b*c| + 2*|b*d| + 2*|c*d|)^(1/2))
sigma_1 = sqrt(a^2 + b^2)
sigma_1 = sqrt(a^2 + c^2)
sigma_1 = sqrt(b^2 + d^2)
sigma_1 = sqrt((a^2 + b^2 + c^2 + d^2)^(1/2))
sqrt(|a|^2 + |b|^2 + |c|^2 + |d|^2)
M := matrix([a, b, c, d]);
norm(M, Infinity);
norm(M, 1);
Simplify(norm(M, 2));
norm(M, Spectral)
max(|a|, |b|, |c|, |d|)
sqrt(|a|^2 + |b|^2 + |c|^2 + |d|^2)
sqrt(|a|^2 + |b|^2 + |c|^2 + |d|^2)
```

עבור המטריצה $\begin{pmatrix} 3 & -1 & 4 \\ -2 & 6 & 1 \\ 2 & 1 & 3 \end{pmatrix}$

1. חשב את הפולינום האופייני.
2. מצא את הערך של הפרמטר t כך ש-7 יהיה ערך עצמי של A וכן המטריצה תהיה סימטרית.
3. חשב את שאר הערכים העצמיים.
4. קבע עפ"י הערכים העצמיים אם המטריצה הפיכה.
5. מצא וקטורים עצמיים.
6. אם ניתן, מצא מטריצה אלכסונית הדומה למטריצה.

```

reset():
use(linalg):
Warning: Identifier "laplacian" already has a value. It is not exported. [use]
Warning: Identifier "hessian" already has a value. It is not exported. [use]
Warning: Identifier "transpose" already has a value. It is not exported. [use]
Warning: Identifier "potential" already has a value. It is not exported. [use]
Warning: Identifier "jacobian" already has a value. It is not exported. [use]
Warning: Identifier "vectorPotential" already has a value. It is not exported. [use]
Warning: Identifier "curl" already has a value. It is not exported. [use]
Warning: Identifier "gradient" already has a value. It is not exported. [use]
Warning: Identifier "transpose" already has a value. It is not exported. [use]
Warning: Identifier "det" already has a value. It is not exported. [use]
Warning: Identifier "divergence" already has a value. It is not exported. [use]

```

```
A:=matrix([[3,-t,4],[-2,6,t],[2*t,t,3]]);
```

$$\begin{pmatrix} 3 & -t & 4 \\ -2 & 6 & t \\ 2t & t & 3 \end{pmatrix}$$

```
CharPoly:=charpoly(A, x)
```

$$x^3 - 12x^2 + (-t^2 - 10t + 45)x + 2t^3 + 3t^2 + 62t - 54$$

```
t_opt:=solve(Simplify(subs(expr(CharPoly), x=7)), t)
```

$$[-2, 2]$$

```
A1:=subs(A, t=-2)
```

$$\begin{pmatrix} 3 & 2 & 4 \\ -2 & 6 & -2 \\ -4 & -2 & 3 \end{pmatrix}$$

We have got a non symmetric matrix

```
A2:=subs(A, t=2)
```

$$\begin{pmatrix} 3 & -2 & 4 \\ -2 & 6 & 2 \\ 4 & 2 & 3 \end{pmatrix}$$

We have got a symmetric matrix, thus t=2.

```
eigenvalues(A2, Multiple)
```

$$[[[-2, 1], [7, 2]]]$$

אף אחד מהערבים העצמיים אינו 0 ולכן המטריצה הפיכה

```
EigenV:=Simplify(linalg:eigenvectors(A2))
```

$$\left[\left[\begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix} \right], \left[7, 2 \right] \left[\begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \right] \right]$$

```
EigenVMatrix:=EigenV[1][3][1].EigenV[2][3][1].EigenV[2][3][2]
```

$$\begin{pmatrix} -1 & -1 \\ -1 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$$

```
det(EigenVMatrix)
```

$$-\frac{2}{3}$$

הפיכה ולכן יש מטריצה אלכסונית שדומה לה

```
EigenMatrix^-1 * A2 * EigenVMatrix
```

$$\begin{pmatrix} -2 & 0 & 0 \\ 0 & 7 & 0 \\ 0 & 0 & 7 \end{pmatrix}$$

מצא מטריצה דומה למטריצה $\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$

```

reset():
use(linalg):
Warning: Identifier "laplacian" already has a value. It is not exported. [use]
Warning: Identifier "hessian" already has a value. It is not exported. [use]
Warning: Identifier "transpose" already has a value. It is not exported. [use]
Warning: Identifier "potential" already has a value. It is not exported. [use]
Warning: Identifier "jacobian" already has a value. It is not exported. [use]
Warning: Identifier "vectorPotential" already has a value. It is not exported. [use]
Warning: Identifier "curl" already has a value. It is not exported. [use]
Warning: Identifier "gradient" already has a value. It is not exported. [use]
Warning: Identifier "transpose" already has a value. It is not exported. [use]
Warning: Identifier "det" already has a value. It is not exported. [use]
Warning: Identifier "divergence" already has a value. It is not exported. [use]

```

```
A:=matrix([[1,2],[3,4]]);
```

```
B:=matrix([[a,b],[c,d]]);
```

```
Expr1:=det(A)=det(B);
```

```
Expr2:=tr(A)=tr(B);
```

```
Expr3:=subs(Expr1, Expr2), (b=2, c=1)
```

$$-2 = ad - bc$$

$$5 = a + d, -2 = ad - 2$$

```
solve(Expr3, {a, d})
```

$$[[{a=0, d=5}, {a=5, d=0}]]$$

```
B:=subs(B, {a=0, d=5, b=2, c=1});
```

$$\begin{pmatrix} 0 & 2 \\ 1 & 5 \end{pmatrix}$$

```
addRow(multRow(swapRow(gaussElim(A), 1, 2), 1, -1), 1, 2, 1.5)
```

$$\begin{pmatrix} 0 & 2 \\ 1 & 5 \end{pmatrix}$$